



State 1:  
 maxBalls = passed in value (e.g. 2)  
 askRobot = passed inv value (e.g. true)  
 save passed in timer  
 reset timer

have ball state:  
 if (maxBalls <= 0) then done shootin  
 if (!askRobot OR broken) then goto shoot  
 shoot  
 if (have ball) then goto shoot  
 if (time expired) then done shooting  
 wait

done shoot state:  
 decrement maxBalls